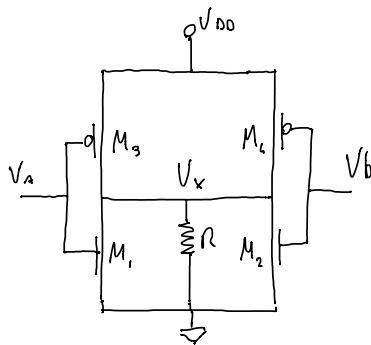


ES. 1



$$V_{TN} = 0.5V$$

$$\beta_N = \beta_P = 500 \mu A/V^2 = \beta$$

$$V_{TP} = -0.5V$$

$$V_{DD} = 5V$$

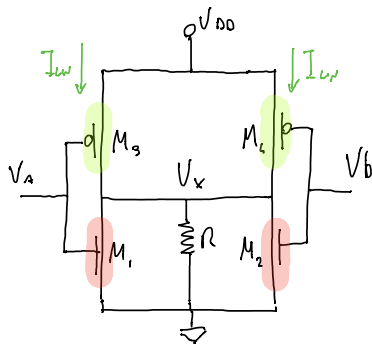
$$R = 10 k\Omega$$

→ imponendo $V_b = 0$ calcolare V_x per diversi valori di V_a

→ potenza dissipata ...

→ po: di max della con $V_b = V_{DD}$

$$V_b = 0V, V_a = 0V$$



→ condizione per cui PMOS SATURATO?

$$V_{SD} < V_{GS} - V_{TP} \Rightarrow \text{LIN}$$

→ supponiamo che PMOS LINEARE

$$I_{LIN} = \frac{\beta_P}{2} \cdot [2(V_{GS} + V_{TP}) \cdot V_{SD} - V_{SD}^2]$$

$$V_x = R \cdot I_R = R \cdot 2 I_{LIN}$$

$$= 10 \cdot 10^3 \cdot 2 \cdot \frac{0.5 \cdot 10^{-3}}{2} \cdot [2 \cdot (5 - 0.5) \cdot (5 - V_x) - (5 - V_x)^2] =$$

$$\Rightarrow V_x = \left\{ 4.89, -4.09 \right\}$$

non accettabile

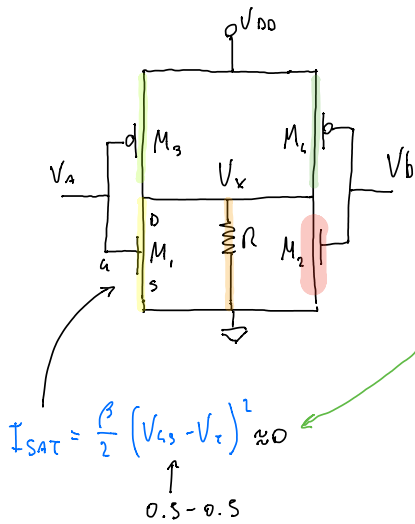
$$\Rightarrow V_{SD} = 5 - 4.89$$

è minore di $V_{GS} - V_{TP}$?

→ LINEARE

PMOS TRIODO (ELW) $V_x = 4.89$

$V_D = 0V$, $V_{in} = V_{TN} \rightarrow$ si accende NMOS



$$\frac{V_x}{R_1} + I_{M1} = I_{M3} + I_{M4} = 2 I_{LIN}$$

$L \approx 0$

$\rightarrow$ sono poco delle due calcoli, per
 sono stessa calcoli

IPOTESI: $M_{3,4}$ TRIODI M_1 SATURO

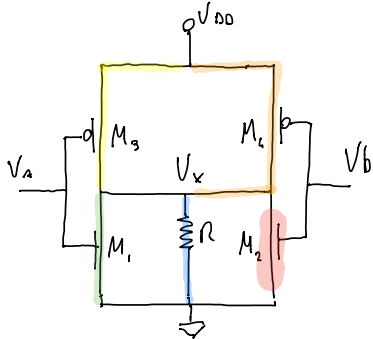
$$V_x = R \cdot \frac{\beta}{2} 2 \left[2 \cdot (5 - 0.5 - 0.5) (5 - V_x) (5 - V_x)^2 \right]$$

$$= 75 + 10 V_x - 5 V_x^2$$

$V_x = 4.88 \rightarrow$ circa uguale a per
 HA SENSO

EFFETTI TRASCURABILI

$V_D = 0$, $V_A = V_x$



IPOTESI PER $M_1, M_3 = SAT \leftarrow$ osservando
 grafico?
 $M_4 = LIN$

$$\frac{V_x}{R} + I_{SAT1} = I_{SAT3} + I_{LIN4}$$

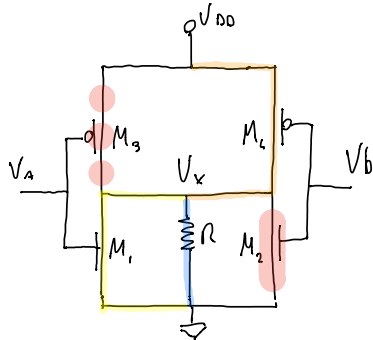
$$\frac{V_x}{R} = \frac{\beta}{2} (V_{DD} - V_x - V_T)^2 + \frac{\beta}{2} [2 (V_{DD} - V_T) \cdot (V_{DD} - V_x) - (V_{DD} - V_x)^2] - \frac{\beta}{2} (V_x - V_T)^2$$

$$= \frac{\beta}{2} \left\{ (4.5 - V_x)^2 + [9(5 - V_x) - (25 + V_x^2 - 10 V_x)] - (V_x^2 + 0.25 - V_x) \right\}$$

$$= \frac{\beta}{2} \left\{ -V_x^2 - 7 V_x + 40 \right\}$$

$$\rightarrow V_x = \frac{\beta}{2} \left\{ -V_x^2 - 7 V_x + 40 \right\} \cdot R = 3.63$$

$$V_B = 0 \quad V_A = V_{DD} - V_T \rightarrow \text{seguito speguito pmos}$$



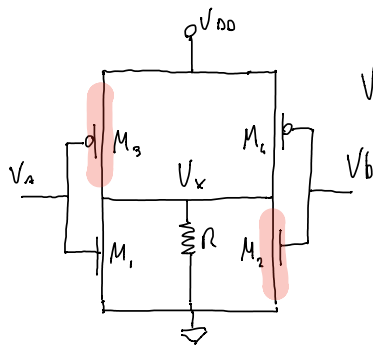
M_3 va in pinch-off $\rightarrow$ IPOTESI SATURO

$$V_x = R(I_{M3} + I_{M4,UP} - I_{M1,UN})$$

$$= \frac{R\beta}{2} \left\{ \left[2(V_{DD} - V_T)(V_{DD} - V_x) - (V_{DD} - V_x)^2 \right] - \left[2(V_{DD} - V_T) \cdot V_x - V_x^2 \right] \right\} = \dots$$

$$V_x = 2.7$$

$$V_B = 0, \quad V_A = V_{DD}$$

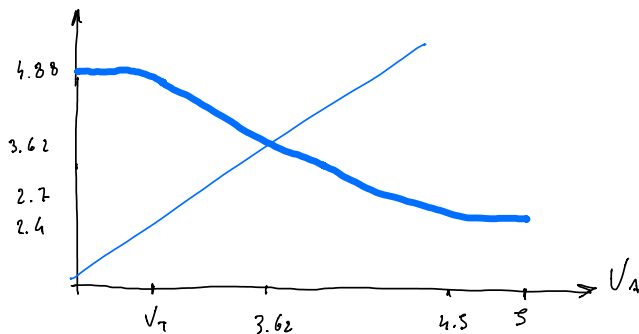


$\rightarrow$ simile a configurazione precedente

$$V_x = \frac{R\beta}{2} \left\{ \left[2(V_{DD} - V_T)(V_{DD} - V_x) - (V_{DD} - V_x)^2 \right] - \left[2(V_{DD} - V_T) \cdot V_x - V_x^2 \right] \right\}$$

$$V_x = 2.38$$

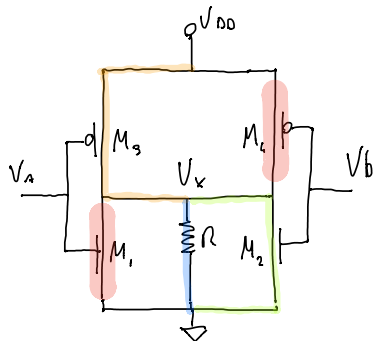
GRAFICO



$\rightarrow$ non è un buon invertitore
for solo clock.

SECONDA PARTE

$$V_B = V_{DD}, V_A = 0$$



IPOTESI: M3 LINEARE
M2 LINEARE

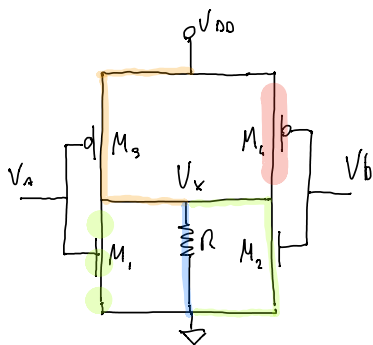
$$0 = \frac{V_x}{R} + I_{2LIN} - I_{3LIN}$$

$$= \frac{V_x}{R} + \frac{\beta}{2} \left\{ \left[2(V_{DD} - V_T)V_x - V_x^2 \right] - \left[2(V_{DD} - V_T)(V_{DD} - V_x) - (V_{DD} - V_x)^2 \right] \right\}$$

$$= V_x + 2.5 \left\{ 9V_x - V_x^2 - 4.5 + 9V_x + 2.5V_x^2 - 10V_x \right\} =$$

$$\rightarrow \text{FAI MACINARE A SOLVER()} \quad V_x = 2.38$$

$$V_B = V_{DD}, V_A = V_T$$

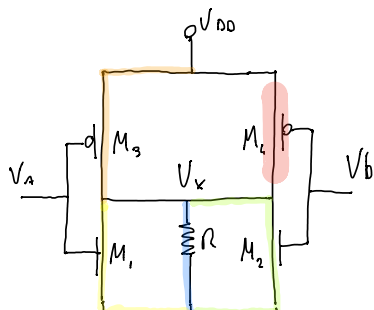


→ sogliare accurate, correte trascurabile

→ USUALE A PAMT BESSUNO E NDO
NUMERO CHE MANCA

$$V_x = 2.02$$

$$V_B = V_{DD}, V_A = V_x$$



M1 M3 M2
SAT, SAT, LIN

$$0 = \frac{V_x}{R} + I_{M1SAT} + I_{M2SAT} - I_{M3SAT}$$

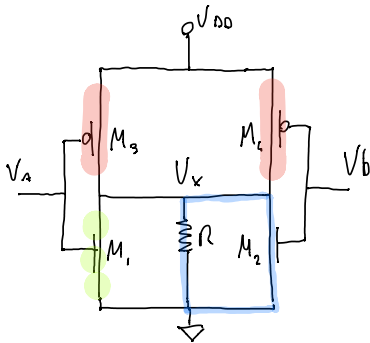
$$= \frac{V_x}{R} + \frac{\beta}{2} (V_x - V_T)^2 - \frac{\beta}{2} (4.5V_x)^2 + \frac{\beta}{2} \left[2(4.5)V_x - V_x^2 \right] =$$



$$= V_x + 2.5 \left[(V_x - 0.5)^2 - 20.25 - V_x^2 + 2V_x + 9V_x - V_x^2 \right] =$$

$$V_x = 1.23$$

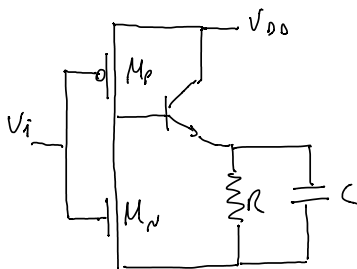
$$V_B = V_{DD}, \quad V_A = V_{DD} - V_T$$



→ Q VGLI SOPRA COME PAVI!

$$V_k = 0$$

ES. 2



$$V_{DD} = 3.3 \quad V_T = 0.4 \quad V_x = 0.75 \quad \beta_F = 50$$

$$\beta = 1.2 \cdot 10^{-3} \quad R = 500 \quad C = 1 \cdot 10^{-12}$$

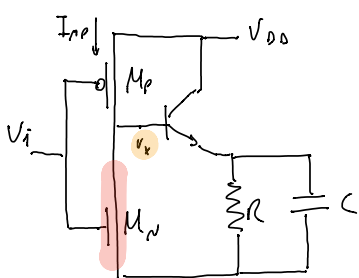
MODELLO A SOLI $V_{CE\text{ sat}} = 0$

V_i SIN 100 MHz 50%.

→ potenza media dissipata su α componente dinamica

→ tempo propagazione HL, qual'è usch per da bene al alla

$$V_i = 0 \quad M_N \text{ OFF}$$



$$V_x \text{ AUTO}$$

REGIONE NORMALE O SAT?

→ COLLEGATO A VDD - SPON FORZA LINEARE

$$I_{MP} = \beta \left\{ (V_{DD} - V_T)(V_{DD} - V_x) - \frac{(V_{DD} - V_x)^2}{2} \right\}$$

→ difficile da farlo reale su carta e
già a satura

→ bene non si può accettare con potenza per
alto di VDD → NO SAT

→ Z_{MP} è incognita

$$I_E = \frac{V_u}{R} \quad I_P = I_B = \frac{I_E}{\beta + 1} \Rightarrow I_P = \frac{V_u}{R(\beta + 1)} = \frac{V_x - V_u}{R(\beta + 1)}$$

→ non si può fare componente dinamica, come se
condizione non c'è

$$V_u = V_x - V_u \quad V_x = V_u + V_u$$

$$I_P = \beta \left\{ (3.5 - 0.4)(3.5 - 0.75 - V_u) - \frac{(3.5 - 0.75 - V_u)^2}{2} \right\} =$$

$$= \beta \left\{ 8.32 - 3.1 V_u - 3.78 - \frac{V_u^2}{2} + 2.75 V_u \right\} = \quad I_P = \frac{V_u}{R(\beta + 1)}$$

$$= \beta \left\{ 4.74 - 0.35 V_u - 0.5 V_u^2 \right\} \Rightarrow V_x = V_u + V_u$$

$$V_u = 2.72 \quad V_x = 3.47$$

→ POTENZA STATICA

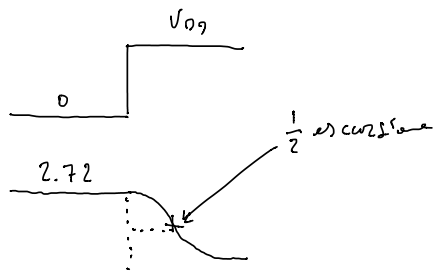
$$P = V \cdot I \quad I = I_R \quad I = \frac{V_u}{R}$$

$$P = 19 \text{ mW} \quad \text{quindi } V_i = 0$$

se ingresso alto, uscita = 0 → $P = 0$

$$\dots \boxed{0} \boxed{19 \text{ mW}} \boxed{0} \boxed{19} \dots \rightarrow \text{QUINDI POT MEDIA} = \frac{P}{2}$$

→ TEMPO PROPAGAZIONE



$$t_{pHL} = \int_{V_m}^{\frac{V_m}{2}} -\frac{RC}{V_m} dV_r$$

$$t_{pHL} = RC \left[\ln |V_m| - \ln \frac{|V_m|}{2} \right] =$$

$$= 500 \cdot [\ln(2.8) - \ln(1.4)] = 346 \text{ ps}$$

→ considerare solo la resistenza

$$I_C = -I_R$$

$$C \frac{dV_m}{dt} = -\frac{V_m}{R}$$

$$\int dt = -\frac{RC}{V_m} \int dV_m$$

↓
integrando



da equazione
pf